

Variables and loops: Hoare logic

Xavier Leroy

Collège de France, chair of software sciences xavier.leroy@college-de-france.fr

Foundations of Hoare logic

Hoare triples

"Weak" triples:



Intuitive meaning:

"If command *c*, started in an initial state satisfying *P*, terminates, then the final state satisfies *Q*."

Later we'll see "strong" triples [*P*] *c* [*Q*] that guarantee termination: "command *c*, started in an initial state satisfying *P*, always terminates, and the final state satisfies *Q*."

Arithmetic expressions:

$$a ::= x$$
program variables $| 0 | 1 | \dots$ constants $| a_1 + a_2 | a_1 \times a_2 | \dots$ operations

Boolean expressions:

$$b ::= a_1 \le a_2 \mid \dots$$
 comparisons
 $\mid b_1 \text{ and } b_2 \mid \text{not } b \mid \dots$ connectives

Commands:

C ∷= skip	empty command
x := a	assignment
c ₁ ; c ₂	sequence
if b then c_1 else c_2	conditional
while b do c	loop

One rule for each kind of command.

 $\{P\}$ skip $\{P\}$ $\{Q[x \leftarrow a]\} x := a \{Q\}$ $\{P\} c_1 \{Q\} \{Q\} c_2 \{R\}$ $\{P\} c_1; c_2 \{R\}$ $\{P \land b\} c_1 \{Q\} \{P \land \neg b\} c_2 \{Q\}$ $\{P\}$ if b then c_1 else c_2 $\{Q\}$ $\{P \land b\} c \{P\}$

 \set{P} while b do c $\set{P \land \neg b}$

The consequence rule:

$$\frac{P \Rightarrow P' \quad \{P'\} c \{Q'\} \quad Q' \Rightarrow Q}{\{P\} c \{Q\}}$$

Can also be presented as two rules: one that strengthens the precondition, another that weakens the postcondition.

$$\frac{P \Rightarrow P' \quad \{P'\} c \{Q\}}{\{P\} c \{Q\}} \qquad \qquad \frac{\{P\} c \{Q'\} \quad Q' \Rightarrow Q}{\{P\} c \{Q\}}$$

Note: the top rule is derivable from the bottom two rules, and conversely.

$$\begin{array}{c} \left\{ \begin{array}{c} 0=0 \wedge 1=1 \right\} x := 0 \; \left\{ \begin{array}{c} x=0 \wedge 1=1 \right\} \\ \left\{ \begin{array}{c} x=0 \wedge 1=1 \right\} y := 1 \; \left\{ \begin{array}{c} x=0 \wedge y=1 \right\} \end{array} \end{array} \right. \\ \hline \left\{ \begin{array}{c} \top \Rightarrow 0=0 \wedge 1=1 \end{array} \right\} x := 0; \\ y:=1 \; \left\{ \begin{array}{c} x=0 \wedge y=1 \right\} \end{array} \end{array} \end{array} \\ \hline \left\{ \left\{ \begin{array}{c} \top \end{array} \right\} x := 0; \\ y:=1 \; \left\{ \begin{array}{c} x=0 \wedge y=1 \right\} \end{array} \right\} \end{array} \end{array}$$

A more compact notation, as an IMP program annotated with assertions:

$$\{ \top \} \Rightarrow \\ \{ 0 = 0 \land 1 = 1 \} \\ x := 0; \\ \{ x = 0 \land 1 = 1 \} \\ y := 1 \\ \{ x = 0 \land y = 1 \}$$

Verifying a "real" program: Euclidean division

 $\{0 \leq a\} \Rightarrow \{a = b \cdot 0 + a \land 0 \leq a\}$ $\mathbf{r} := \mathbf{a};$ $\{ a = b \cdot 0 + r \land 0 < r \}$ q := 0; $\{a = b \cdot q + r \land 0 \leq r\}$ while $r \ge b do$ $\{a = b \cdot q + r \land 0 < r \land r > b\} \Rightarrow$ $\{a = b \cdot (q+1) + (r-b) \land 0 < r-b\}$ r := r - b; $\{a = b \cdot (q+1) + r \land 0 < r\}$ q := q + 1 $\{a = b \cdot q + r \land 0 < r\}$

done

$$\left\{ \begin{array}{l} \mathbf{a} = \mathbf{b} \cdot \mathbf{q} + \mathbf{r} \land \mathbf{0} \leq \mathbf{r} \land \mathbf{r} < \mathbf{b} \\ \left\{ \mathbf{q} = \mathbf{a}/\mathbf{b} \land \mathbf{r} = \mathbf{a} \bmod \mathbf{b} \right\} \end{array}$$

1. Write an IMP program that sets ${\bf x}$ to the maximum of the values of ${\bf x}$ and of ${\bf y}.$

2. Specify this program in Hoare logic.

3. Verify the program against this specification.

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We conclude using the rule for conditional.

Many programs satisfy this specification...

$$\begin{array}{ll} \{\top\} & x := y & \{x = \max(x, y)\} \\ \{\top\} & y := x & \{x = \max(x, y)\} \\ \{\top\} & x := 1; y := 0 & \{x = \max(x, y)\} \end{array}$$

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This is the wrong specification! We wanted to say

The value of x at the end of the program is the maximum of the values of x and y at the beginning of the program.

One solution is to use mathematical variables α, β, \ldots , distinct from program variables x, y, . . . :

$$\{ \mathbf{x} = \alpha \land \mathbf{y} = \beta \} \mathsf{c} \{ \mathbf{x} = \mathsf{max}(\alpha, \beta) \}$$

These **auxiliary variables** are universally quantified implicitly before the triple:

$$\forall \alpha, \beta, \quad \{ \mathbf{x} = \alpha \land \mathbf{y} = \beta \} \mathsf{c} \{ \mathbf{x} = \mathsf{max}(\alpha, \beta) \}$$

Alternative: in the specification, use variables from the programming language that do not occur in the program being specified:

$$\{\mathbf{x} = \mathbf{z}\} c \{\mathbf{x} = \max(\mathbf{z}, \mathbf{y})\}$$
 where z not free in c

These ghost variables *z* preserve their values during execution of *c*, enabling the postcondition to talk about the state "before".





Intuitive meaning:

"Command c, started in an initial state satisfying P, terminates in a final state satisfying Q."

Only loops can cause non-termination ⇒ for all other IMP constructors, the "strong" rules are similar to the "weak" rules.

 $[P] \operatorname{skip} [P] \qquad [Q[x \leftarrow a]] x := a [Q]$ $\frac{[P] c_1[Q] \quad [Q] c_2[R]}{[P] c_1; c_2[R]} \qquad \frac{[P \land b] c_1[Q] \quad [P \land \neg b] c_2[Q]}{[P] \operatorname{if} b \operatorname{then} c_1 \operatorname{else} c_2[Q]}$ $\frac{P \Rightarrow P' \quad [P'] c [Q'] \quad Q' \Rightarrow Q}{[P] c [Q]}$

Using a variant: an expression *a*, with nonnegative values, that decreases at every loop iteration.

$$\forall \alpha, [P \land b \land a = \alpha] c [P \land 0 \leq a < \alpha]$$

[P] while b do $c [P \land \neg b]$

The loop must terminate after at most *N* iterations, where *N* is the initial value of variant *a*.

Note: with nested loops, the termination of each loop is verified independently of the other loops. (Unlike in Turing 1949 and Floyd 1967.)

Verifying termination of Euclidean division

The variant is the variable r.

 $\{0 < a \land 0 < b\} \Rightarrow \{a = b \cdot 0 + a \land 0 < a \land 0 < b\}$ $\mathbf{r} := \mathbf{a}$: $\{a = b \cdot 0 + r \land 0 < r \land 0 < b\}$ q := 0; $\{a = b \cdot q + r \land 0 < r \land 0 < b\}$ while $r \ge b do$ $\{a = b \cdot q + r \land 0 \leq r \land 0 < b \land r \geq b \land r = \alpha\} \Rightarrow$ $\{a = b \cdot (q+1) + (r-b) \land 0 < r-b \land 0 < b\}$ $\land \mathbf{0} \leq \mathbf{r} - \mathbf{b} < \alpha \}$ r := r - b; $\{a = b \cdot (q+1) + r \land 0 \leq r \land 0 < b \land 0 \leq r < \alpha\}$ q := q + 1 $\{a = b \cdot q + r \land 0 < r \land 0 < b \land 0 < r < \alpha\}$

done

$$\left\{ \begin{array}{l} \mathbf{a} = \mathbf{b} \cdot \mathbf{q} + \mathbf{r} \land \mathbf{0} \leq \mathbf{r} \land \mathbf{r} < \mathbf{b} \\ \left\{ \mathbf{q} = \mathbf{a}/\mathbf{b} \land \mathbf{r} = \mathbf{a} \bmod \mathbf{b} \right\} \end{array}$$

We can use several variants a_1, \ldots, a_n and a well-founded order \prec over *n*-tuples of integers. (Typically, lexicographic order.)

$$\forall \alpha_1, \dots, \alpha_n, \ [P \land b \land (a_1, \dots, a_n) = (\alpha_1, \dots, \alpha_n)]$$

$$c$$

$$[P \land (a_1, \dots, a_n) \prec (\alpha_1, \dots, \alpha_n)]$$

[P] while b do c $[P \land \neg b]$

Adding rules to the logic

A derived rule: conditional without else

Notation: if b then $c \stackrel{def}{=} if b$ then c else skip

$$\{ \mathsf{P} \land b \} \mathsf{c} \{ \mathsf{Q} \} \quad \mathsf{P} \land \neg b \Rightarrow \mathsf{Q}$$

 $\{P\}$ if b then $c\{Q\}$

Proof.

Here is the derivation:

$$\frac{\{P \land b\} c \{Q\}}{\{P \land b\} c \{Q\}} \frac{P \land \neg b \Rightarrow Q \quad \{Q\} \operatorname{skip} \{Q\}}{\{P \land \neg b\} \operatorname{skip} \{Q\}}$$

A derived rule: the do...while loop

Notation: do c while $b \stackrel{def}{=} c$; while b do c

$$\{ P \} c \{ Q \} \quad Q \land b \Rightarrow P$$

$$\set{P}$$
 do c while b $\set{Q \land \neg b}$



$$\frac{\{P\} c \{Q\}}{\{Q\} \text{ while } b \text{ do } c \{Q\}}$$

$$\frac{\{P\} c \{Q\}}{\{Q\} \text{ while } b \text{ do } c \{Q \land \neg b\}}{\{P\} c; \text{ while } b \text{ do } c \{Q \land \neg b\}}$$

Notation: if *h*, *i* are two distinct variables,

for
$$i = \ell$$
 to h do c $\stackrel{def}{=}$ $i := \ell$; while $i \le h$ do $(c; i := i + 1)$

We can derive a strong triple that guarantees loop termination, provided the loop body *c* contains no assignments to *i* nor to *h*.

$$\frac{[P \land i \le h] c [P[i \leftarrow i+1]] \quad i, h \text{ not assigned to in } c}{[P[i \leftarrow \ell]] \text{ for } i = \ell \text{ to } h \text{ do } c [P \land i > h]}$$

The variant is the expression h - i + 1, which decreases by 1 at each iteration.

$$\{P\} \mathtt{x} := a \{ \exists x_0, \mathtt{x} = a[\mathtt{x} \leftarrow x_0] \land P[\mathtt{x} \leftarrow x_0] \}$$

Proof.

Write $Q \stackrel{def}{=} \exists x_0, x = a[x \leftarrow x_0] \land P[x \leftarrow x_0].$ $\frac{P \Rightarrow Q[x \leftarrow a] \quad \{ Q[x \leftarrow a] \} x := a \{ Q \}}{\{ P \} x := a \{ Q \}}$ Indeed, $Q[x \leftarrow a] = \exists x_0, a = a[x \leftarrow x_0] \land P[x \leftarrow x_0][x \leftarrow a]$ $= \exists x_0, a = a[x \leftarrow x_0] \land P[x \leftarrow x_0]$ and it suffices to take $x_0 = x.$ Conjunction, disjunction, quantification:

 $\frac{\{P_1\} c \{Q_1\} \quad \{P_2\} c \{Q_2\}}{\{P_1 \land P_2\} c \{Q_1 \land Q_2\}} \qquad \frac{\{P_1\} c \{Q_1\} \quad \{P_2\} c \{Q_2\}}{\{P_1 \lor P_2\} c \{Q_1 \lor Q_2\}}$ $\frac{\forall x \in X, \{P(x)\} c \{Q(x)\} \quad X \neq \emptyset}{\{\forall x \in X. P(x)\} c \{\forall x \in X. Q(x)\}} \qquad \frac{\forall x \in X, \{P(x)\} c \{Q(x)\}}{\{\exists x \in X. P(x)\} c \{\exists x \in X. Q(x)\}}$

Proof.

Induction on c and inversion on the derivations of $\{P_1\} c \{Q_1\}$, $\{P_2\} c \{Q_2\}$, etc.

Growing the programming language

Goto considered harmful ... or not?

Commands: $c ::= ... | goto \ell | \ell : c$

We need to associate an invariant $L(\ell)$ to each label ℓ .

The triples become $L \vdash \{P\} c \{Q\}$.

$$L \vdash \{L(\ell)\} \text{goto} \ \ell \ \{\bot\} \qquad \qquad \frac{L \vdash \{L(\ell)\} \ \mathsf{c} \ \{Q\}}{L \vdash \{L(\ell)\} \ \ell : \mathsf{c} \ \{Q\}}$$

Enable programs to have several different behaviors.

$$c ::= \dots$$

$$|c_1| c_2 \qquad \text{execute either } c_1 \text{ or } c_2$$

$$|x := \text{choose}(N) \qquad \text{set } x \text{ to a number between 0 and } N-1$$

$$| \text{havoc } x \qquad \text{set } x \text{ to an arbitrary number}$$

The other constructions can be derived from havoc:

$$\begin{array}{rcl} x := \operatorname{choose}(N) &\approx & \operatorname{havoc} x; \ x := x \bmod N \\ & & c_1 \parallel c_2 &\approx & x := \operatorname{choose}(2); \mbox{if } x = 0 \ \mbox{then } c_1 \ \mbox{else } c_2 \\ & x := \operatorname{choose}(N) &\approx & x := 0 \ \mbox{if } x := 1 \ \mbox{if } x := N - 1 \end{array}$$

The rule for choice:

$$\frac{\{P\} c_1 \{Q\} \{P\} c_2 \{Q\}}{\{P\} c_1 \| c_2 \{Q\}}$$

The axiom for choose:

$$\{ Q[\mathbf{x} \leftarrow \mathbf{0}] \land \dots \land Q[\mathbf{x} \leftarrow \mathbf{N} - \mathbf{1}] \} \mathbf{x} := \operatorname{choose}(\mathbf{N}) \{ Q \}$$

or $\{ \forall \alpha, \ \mathbf{0} \le \alpha < \mathbf{N} \Rightarrow Q[\mathbf{x} \leftarrow \alpha] \} \mathbf{x} := \operatorname{choose}(\mathbf{N}) \{ Q \}$

The axiom for havoc:

$$\{ \forall \alpha, Q[x \leftarrow \alpha] \} \text{ havoc } x \{ Q \}$$
or $\{ Q[x \leftarrow y] \} \text{ havoc } x \{ Q \}$ if y does not occur in Q

С

Run-time assertions introduce the possibility of run-time failure.

:::=	
assert b	(<i>b</i> is a Boolean expression;
	appropriate for run-time checking)
assert A	(A is a logical assertion;
	appropriate for static verification)

Verification must guarantee the absence of run-time failures. Hence the rule:

$$\{P \land A\}$$
 assert A $\{P \land A\}$

Evaluating an arithmetic expression *a* or Boolean expression *b* can also fail at run-time: integer division by zero, arithmetic overflow, etc.

We can characterize absence of failures as a predicate Def:

 $ext{Def}(cst) = ext{Def}(x) = op$ $ext{Def}(a_1 + a_2) = ext{Def}(a_1) \wedge ext{Def}(a_2) \wedge ext{MIN} \le a_1 + a_2 \le ext{MAX}$ $ext{Def}(a_1/a_2) = ext{Def}(a_1) \wedge ext{Def}(a_2) \wedge a_2 \neq 0 \wedge ext{MIN} \le a_1/a_2 \le ext{MAX}$ $ext{Def}(a_1 \le a_2) = ext{Def}(a_1) \wedge ext{Def}(a_2)$

(etc.)

In the rules of the logic, we add preconditions to guarantee that all expressions evaluate without errors.

$$\{Q[x \leftarrow a] \land \texttt{Def}(a)\} x := a \{Q\}$$

$$\left\{ \, P \wedge b \, \right\} \, c_1 \left\{ \, Q \, \right\} \quad \left\{ \, P \wedge \neg b \, \right\} \, c_2 \left\{ \, Q \, \right\}$$

 $\{P \land \mathtt{Def}(b)\} \texttt{ if } b \texttt{ then } c_1 \texttt{ else } c_2 \{Q\}$

 $\{P \land b\} c \{P \land \mathsf{Def}(b)\}$

 $\{P \land \mathsf{Def}(b)\}$ while b do $c \{P \land \neg b\}$

Connections with semantics: soundness of Hoare logic
Hoare's viewpoint:

- A "bespoke" logic
- that "talks" about program variables (x, ...) and programming language operators (+, and, ...)
- An assertion = a proposition of this bespoke logic.

A more practical viewpoint:

- An "off the shelf" logic, typically first-order logic + arithmetic.
- "Talks" about program variables and programming language operators via a translation.
- An assertion = a predicate on the memory store.

A store s associates a value to each program variable.

Store $s ::= variable \rightarrow value$

An assertion *P* (mentioning program variables x, y, ...) is interpreted as a predicate on the store s:

$$\llbracket P \rrbracket s = P[x \leftarrow s(x), y \leftarrow s(y), \ldots]$$

Example

The assertion $0 \le x < y$ denotes the predicate $\lambda s. 0 \le s(x) < s(y)$.

We assume given a denotational semantics for expressions of the language: each expression a is interpreted as a function [a]: store \rightarrow value. Typically:

 $[x] s = s(x) [a_1 + a_2] = [a_1] \oplus [a_2]$ $[cst] s = cst [a_1 * a_2] = [a_1] \otimes [a_2]$

Operators \oplus , \otimes denote addition and multiplication of the programming language. For example, for arithmetic modulo 2³²

 $n_1 \oplus n_2 = \operatorname{norm}(n_1 + n_2)$ $n_1 \otimes n_2 = \operatorname{norm}(n_1 \times n_2)$ $\operatorname{norm}(n) = n \mod 2^{32}$ (unsigned integers) $\operatorname{norm}(n) = (n + 2^{31}) \mod 2^{32} - 2^{31}$ (signed integers)

$$\{ \mathbf{Q}[\mathbf{x} \leftarrow \mathbf{a}] \} \mathbf{x} := \mathbf{a} \{ \mathbf{Q} \}$$

In the assignment rule, what does $Q[x \leftarrow a]$ mean?

It is the predicate $\llbracket Q \rrbracket s$ where $\llbracket x \rrbracket s$ (that is, s(x)) is replaced by $\llbracket a \rrbracket s$.

Example:

$$\begin{bmatrix} (x < 10) [x \leftarrow x + 1] \end{bmatrix} s = (s(x) < 10) [s(x) \leftarrow \llbracket x + 1 \rrbracket s]$$
$$= \llbracket x + 1 \rrbracket s < 10 = (s(x) \oplus 1) < 10$$

By construction, we have

$$\llbracket Q[x \leftarrow a] \rrbracket s = \llbracket Q \rrbracket (s[x \leftarrow \llbracket a \rrbracket s])$$

This provides semantic justification for Hoare's assignment rule.

To model arithmetic errors (e.g. division by zero), we can add a special denotation err:

 $\llbracket a \rrbracket \mathsf{s} \in \mathbb{Z} + \{\texttt{err}\}$

The substituted assertion $Q[x \leftarrow a]$ requires $\llbracket a \rrbracket s \neq err$:

$$\llbracket Q[x \leftarrow a] \rrbracket s = \llbracket a \rrbracket s \neq \texttt{err} \land \llbracket Q \rrbracket (s[x \leftarrow \llbracket a \rrbracket s])$$

The Def(a) assertion must guarantee **[**a**]** $s \neq err$.

This provides semantic justification for the modified assignment rule

$$\left\{ \left. \mathsf{Q}[\mathsf{x} \leftarrow a] \land \mathtt{Def}(a) \right\} \mathsf{x} := a \left\{ \left. \mathsf{Q} \right\}
ight\}$$

A semantics for commands must account for

- divergence (non-termination) (while loops, ...)
- run-time errors (1/0, run-time assertions)
- nondeterminism

(choose, havoc, $c_1 \parallel c_2$)

We take an operational semantics based on a reduction relation:

$$egin{array}{ccc} c/s &
ightarrow & c'/s' \ c/s &
ightarrow & {
m err} \end{array}$$

c: command one step c': residual command s: store "before" of execution s': store "after" err: run-time error

Reduction rules for IMP

 $(x := a)/s \rightarrow \text{skip}/s[x \leftarrow [a]]s]$ $(\text{skip}; c_2)/s \rightarrow c_2/s$ $(c_1; c_2)/s \to (c'_1; c_2)/s'$ if $c_1/s \rightarrow c'_1/s'$ $(c_1; c_2)/s \rightarrow \text{err}$ if $c_1/s \rightarrow \text{err}$ (if *b* then c_1 else c_2)/s $\rightarrow c_1/s$ if [[b]] s is true (if *b* then c_1 else c_2)/s $\rightarrow c_2/s$ if **[***b***]** s is false (while $b \text{ do } c)/s \rightarrow \text{skip}/s$ if [[b]] s is false (while $b \operatorname{do} c)/s \rightarrow (c; \text{ while } b \operatorname{do} c)/s$ if s b is true $(havoc x)/s \rightarrow skip/s[x \leftarrow n]$ for any *n* $(\texttt{assert} A)/s \rightarrow \texttt{skip}/s$ if [A] s is true $(\texttt{assert } A)/s \rightarrow \texttt{err}$ if [A] s is false

Reduction sequences

The possible behaviors of a command *c* correspond to sequences of reductions for c/s.

• Termination with final store s': reductions to skip/s'

$$c/s \to c_1/s_1 \to \dots \to \texttt{skip}/s'$$

• Termination on an error: reductions to err

$$c/s \to c_1/s_1 \to \dots \to \texttt{err}$$

• Divergence: infinite reduction sequence

$$c/s \rightarrow \cdots \rightarrow c_n/s_n \rightarrow \cdots$$

• Going wrong: (cannot happen if relation \rightarrow is complete)

$$c/s \to c_1/s_1 \to \dots \to c'/s' \not\to \ \text{ with } c' \neq \texttt{skip}$$

Intuitive interpretation of triples:

{ P } c { Q }	"command c, started in an initial store
	s satisfying P, executes without
	run-time errors, and if it terminates,
	the final store satisfies Q "
[P]c[Q]	"command c, started in an initial store
	s satisfying P, always terminates
	without run-time errors, and the final
	store satisfies Q "

Is this true of all the possible executions of c/s according to the reduction semantics?

Theorem (Semantic soundness of the weak logic)

Assume $\{P\} c \{Q\}$. Let s be a store such that $\llbracket P \rrbracket$ s.

- 1. Safety: it is impossible that $c/s \stackrel{*}{\rightarrow} \texttt{err}$
- 2. Partial correctness: if $c/s \xrightarrow{*} skip/s'$, then $\llbracket Q \rrbracket s'$.

We now outline several proofs. The first proof is inspired by soundness proofs for type systems.

Lemma (Immediate safety and preservation)

Assume $\{P\} c \{Q\}$ and $\llbracket P \rrbracket s$.

- 1. Immediate safety: c/s $\not\rightarrow$ err
- Preservation: if c/s → c'/s', there exists a precondition P' such that { P' } c' { Q } and [[P']] s'.

Proof.

By case analysis on reduction rules $c/s \rightarrow \ldots$ and inversion on the derivation of $\{P\} c \{Q\}$.

Semantic soundness follows easily:

- 1. Safety: assume by way of contradiction that $c/s \xrightarrow{*} c'/s' \rightarrow \text{err.}$ By preservation, there exists P' s.t. $\{P'\}c'\{Q\}$ and $\llbracket P' \rrbracket s'$. By immediate safety, $c'/s' \rightarrow \text{err.}$ Contradiction.
- Partial correctness: assume c/s ^{*}→ skip/s'. By preservation, there exists P' such that { P' } skip { Q } and [[P']] s'. By inversion on { P' } skip { Q }, we have P' ⇒ Q. Therefore, [[Q]] s', as expected.

The tree of reductions



One run of the program = one branch of the tree.

The program always terminates

- = all branches are finite
- = the tree can be described by an inductive predicate

Term *c s Q*: "command *c*, started in store *s*, always terminates, and the final store satisfies *Q*".

[[Q]] s

Term skip S Q

 $\mathsf{c} \neq \texttt{skip} \quad \mathsf{c}/\mathsf{s} \not\rightarrow \texttt{err} \quad (\forall \mathsf{c}', \mathsf{s}', \ \mathsf{c}/\mathsf{s} \rightarrow \mathsf{c}'/\mathsf{s}' \Rightarrow \texttt{Term} \ \mathsf{c}' \ \mathsf{s}' \ \mathsf{Q})$

Term csQ

This is an inductive predicate. Therefore, it does not hold if an infinite sequence of reductions exist.

The semantic triple: "if the initial store satisfies *P*, command *c* terminates in a store satisfying *Q*"

$$\llbracket [P]] c \llbracket Q \rrbracket \stackrel{def}{=} \forall s, \llbracket P \rrbracket s \Rightarrow \texttt{Term} c s Q$$

We show that this definition satisfies the axioms and the inference rules of Hoare logic:

- [[P]] skip [[P]]
- If $[[P]] c_1 [[Q]]$ and $[[Q]] c_2 [[R]]$ then $[[P]] c_1; c_2 [[R]]$
- etc.

Theorem (Semantic soundness of the strong logic)

If [P] c [Q] is derivable, then [[P]] c [[Q]] holds.

Many authors no longer provide an axiomatization of the triples [P] c [Q]. Instead, they take the semantic definition directly:

$$[P] c [Q] \stackrel{def}{=} [[P]] c [[Q]] \stackrel{def}{=} \forall s, \llbracket P \rrbracket s \Rightarrow \texttt{Term} c s Q$$

Then, they show the axioms and the inference rules of the logic as lemmas that hold for this definition.

This makes it possible to reason over programs like in Hoare logic, but with semantic soundness being guaranteed by construction.

This is not in the "axiomatic" spirit of Hoare (1969), but simplifies the formalization and the addition of new rules *a posteriori*. Can we follow the same approach for a weak program logic?

Yes, if we replace the predicate Term $c \ s \ Q$ by a predicate Safe $c \ s \ Q$ stating that executions of c/s do not terminate on an error, and that if they terminate, the final state satisfies Q.

$$\{\!\{ P \}\!\} \mathsf{ c } \{\!\{ Q \}\!\} \quad \stackrel{def}{=} \quad \forall \mathsf{ s }, \ \llbracket P \rrbracket \mathsf{ s } \Rightarrow \mathtt{Safe } \mathsf{ c } \mathsf{ s } Q$$

Just like the Term predicate is naturally inductive, the Safe predicate is naturally coinductive:

[[Q]] s

Safe skip S Q

 $\mathsf{C} \neq \texttt{skip} \quad \mathsf{C}/\mathsf{S} \not\to \texttt{err} \quad \big(\forall \mathsf{C}', \mathsf{S}', \ \mathsf{C}/\mathsf{S} \to \mathsf{C}'/\mathsf{S}' \Rightarrow \texttt{Safe} \ \mathsf{C}' \ \mathsf{S}' \ \mathsf{Q} \big)$

Safe c s Q

A coinductive predicate supports derivations that are infinitely deep. Hence, Safe c s Q holds if c/s diverges without errors (by infinitely many applications of the second rule).

Instead of coinduction, we can use step-indexing:

Safe $c s Q \stackrel{def}{=} \forall n, Safe^n c s Q$

The inductive predicate $\operatorname{Safe}^n c \ s \ Q$ means that executions of c/s do not cause errors during the first *n* execution steps, and satisfy *Q* if they terminate in *n* steps or less.

 $\frac{\llbracket Q \rrbracket s}{\operatorname{Safe}^{n} c \ s \ Q} = \frac{\llbracket Q \rrbracket s}{\operatorname{Safe}^{n+1} \operatorname{skip} s \ Q}$ $\frac{c \neq \operatorname{skip} \quad c/s \not\rightarrow \operatorname{err} \quad (\forall c', s', \ c/s \rightarrow c'/s' \Rightarrow \operatorname{Safe}^{n} c' \ s' \ Q)}{\operatorname{Safe}^{n+1} c \ s \ Q}$

Either with the coinductive definition of Safe or with the step-indexed definition, the weak semantic triple

$$\{\!\{ P \}\!\} \in \{\!\{ Q \}\!\} \quad \stackrel{def}{=} \quad \forall s, \llbracket P \rrbracket s \Rightarrow \texttt{Safe } c \ s \ Q$$

satisfies the axioms and the inference rules of weak Hoare logic:

- {{ P }} skip {{ P }}
- If {{ P }} c_1 {{ Q }} and {{ Q }} c_2 {{ R }} then {{ P }} c_1 ; c_2 {{ R }}
- If {{ $P \land b$ }} c {{ $P \}} then {{ <math>P \}} while b do c {{ <math>P \land \neg b }}$
- etc.

As a corollary, we obtain another proof of semantic soundness for the weak logic:

Theorem (Semantic soundness of the weak logic)

If { P } c { Q } is derivable, then {{ P }} c {{ Q }} holds.

Proof.

By induction on the derivation of $\{P\} c \{Q\}$.

Connections with semantics: completeness of Hoare logic

The converse of semantic soundness:

Can any property of the executions of a program c be expressed as a triple $\{P\} c \{Q\}$ and derived in Hoare logic?

Using semantic triples, we can make the question more precise:

If {{ *P* }} *c* {{ *Q* }} holds, can we derive { *P* } *c* { *Q* }? If [[*P*]] *c* [[*Q*]] holds, can we derive [*P*] *c* [*Q*]? The completeness issue was the topic of many studies in the 1970's because of the following connection between Hoare logic and computability:

Corollary (of semantic soundness)

If $\{\,\top\,\}$ c $\{\,\perp\,\}$ is derivable, then c does not terminate.

If Hoare logic was complete, we would have an equivalence: $\{\top\} c \{\bot\}$ is derivable if and only if c does not terminate.

Reminder: the set of propositions that can be derived in a system of axioms and inference rules is recursively enumerable (r.e.).

The set of derivable triples $\{P\} c \{Q\}$ is r.e.

The set of derivable triples $\{ \top \} c \{ \perp \}$ is r.e. (by "filtering" the enumeration of all derivable triples).

If the logic is complete, the set of programs that do not terminate is r.e.

Consequently, if the logic is complete, the halting problem is decidable!

$$\frac{\mathsf{P} \Rightarrow \mathsf{P}' \quad \{\mathsf{P}'\} c \{\mathsf{Q}'\} \quad \mathsf{Q}' \Rightarrow \mathsf{Q}}{\{\mathsf{P}\} c \{\mathsf{Q}\}}$$

What is the meaning of the premises $P \Rightarrow P'$ and $Q' \Rightarrow Q$?

"Implications that can be derived in a formal logic."
 The set of these implications is r.e., hence { P } c { Q } is r.e., and the logic is incomplete.

(Stephen A. Cook, Soundness and completeness of an axiom system for program verification, SIAM J. Comput., 1978)

We can show that Hoare logic is complete, provided the same "ambient" logic is used

- to interpret the implications P ⇒ P', Q' ⇒ Q in the consequence rule;
- to define semantic triples $\{\{P\}\} \ c \ \{\{Q\}\} \stackrel{def}{=} \forall s, \ \llbracket P \rrbracket \ s \Rightarrow \texttt{Safe} \ c \ s \ Q.$

We define the weakest (liberal) semantic precondition of command *c* with postcondition *Q*:

wpsem $c Q \stackrel{def}{=} \lambda s. \text{Safe} c s Q$

By definition of semantic triples, we have

 $\{\{P\}\} \in \{\{Q\}\}\$ if and only if $P \Rightarrow wpsem c Q$

Lemma (the weakest semantic precondition is derivable)

 $\{ wpsem c Q \} c \{ Q \}$ is derivable in Hoare logic.

Proof.

Induction over c and "inversion" lemmas on the Safe predicate, such as Safe $(c_1; c_2)$ s Q implies Safe c_1 s (wpsem c_2 Q).

Theorem (relative completeness)

If {{ P }} c {{ Q }} is provable in logic L,
then { P } c { Q } can be derived in Hoare logic,
using L for the implications in the consequence rule.

Proof.

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By hypothesis {{ P }} c {{ Q }}, we have P \Rightarrow wpsem c Q.
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By the previous lemma, we can derive $\{ wpsem c Q \} c \{ Q \}$.

We conclude $\{P\} c \{Q\}$ with the consequence rule.

Towards automation: weakest precondition calculus

Deductive verification (reminder)



How to generate the verification conditions? How to minimize the amount of assertions to provide?

Fully-annotated programs

 $\{0 \leq a\} \Rightarrow \{a = b \cdot 0 + a \land 0 \leq a\}$ $\mathbf{r} := \mathbf{a};$ $\{a = b \cdot 0 + r \land 0 < r\}$ q := 0; $\{a = b \cdot q + r \land 0 < r\}$ while r > b do $\{a = b \cdot g + r \land 0 < r \land r > b\} \Rightarrow$ $\{a = b \cdot (q+1) + (r-b) \land 0 < r-b\}$ $\mathbf{r} := \mathbf{r} - \mathbf{b};$ $\{a = b \cdot (q+1) + r \land 0 < r\}$ q := q + 1 $\{a = b \cdot q + r \land 0 \leq r\}$ done $\{a = b \cdot q + r \land 0 \leq r \land r < b\} \Rightarrow$

 $\{q = a/b \land r = a \mod b\}$

Verification conditions: the " \Rightarrow " steps where we apply the consequence rule.

To verify a program fragment c, it is enough to provide

- the precondition P
- the postcondition Q
- a loop invariant *Inv* for each loop in c.

The other logical assertions and the verification conditions can then be obtained by computing weakest preconditions or strongest postconditions. The weakest precondition of a command *c* with postcondition *Q* is an assertion wp c Q such that

- it is a precondition: [wp c Q] c [Q];
- it is the weakest: if [P] c [Q] then $P \Rightarrow wp c Q$.

Consequently:

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[P] c [Q] if and only if P \Rightarrow wp c Q
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Intuition: wp c Q are the necessary hypotheses for program c to compute a result that satisfies the postcondition Q.

Original intuition (Dijkstra, 1975): synthesizing the program *c* by refinement from its postcondition *Q*.

Weakest liberal precondition wlp c Q

Like wp but does not guarantee termination:

 $\{P\} c \{Q\}$ if and only if $P \Rightarrow wlp c Q$

Strongest (liberal) postcondition sp P c slp P c

 $[P] c [Q] \text{ if and only if } \operatorname{sp} P c \Rightarrow Q$ $\{P\} c \{Q\} \text{ if and only if } \operatorname{slp} P c \Rightarrow Q$

Intuition: symbolic execution of c from a state satisfying P.

A non-effective characterization: wlp $c Q = \bigvee \{P \mid \{P\} c \{Q\}\}$

For programs without loops, a definition by induction over c:

$$\begin{split} & \texttt{wlp skip } Q = Q \\ & \texttt{wlp } (x := a) \ Q = Q[x \leftarrow a] \\ & \texttt{wlp } (c_1; c_2) \ Q = \texttt{wlp } c_1 \ (\texttt{wlp } c_2 \ Q) \\ & \texttt{wlp } (\texttt{if } b \texttt{ then } c_1 \texttt{ else } c_2) \ Q = (b \land \texttt{wlp } c_1 \ Q) \lor (\neg b \land \texttt{wlp } c_2 \ Q) \\ & \texttt{wlp } (\texttt{havoc } x) \ Q = \forall n, \ Q[x \leftarrow n] \\ & \texttt{wlp } (\texttt{assert } A) \ Q = A \land Q \end{split}$$

(These equations are valid for wp as well.)
Not computable in general: wlp (while b do c) $Q = \bigvee_i P_i$ with $P_0 = \neg b \land Q$ and $P_{i+1} = b \land wlp c P_i$.

We ask the programmer to annotate each loop by its invariant *Inv*. In this case,

wlp (while^{$$Inv$$} b do c) $Q = Inv$

provided that

 $b \wedge Inv \Rightarrow wlp c Inv$ and $\neg b \wedge Inv \Rightarrow Q$

To compute wp, the programmer should also annotate the loop by the variant that guarantees termination.

A semi-algorithm for deductive verification

To verify $\{P\} c \{Q\}$, assuming all loops in c are annotated:

 Compute wlp c Q and the following verification conditions vc c Q

vc (while^{Inv} b do c)
$$Q = (b \land Inv \Rightarrow wlp c Inv)$$

 $\land (\neg b \land Inv \Rightarrow Q)$
 $\land vc c Inv$
vc skip $Q = \top$
vc $(c_1; c_2) Q = vc c_1 (wlp c_2 Q) \land vc c_2 Q$

and likewise for the other language constructs.

2. Prove $(P \Rightarrow wlp c Q) \land vc c Q$, which is a proposition in ordinary logic, using an automated theorem prover.

Computing and verifying the strongest liberal postcondition

For reference, the equations defining slp:

$$\begin{split} \mathtt{slp} \ P \ \mathtt{skip} &= P \\ \mathtt{slp} \ P \ (x := a) = \exists x_0, \mathtt{x} = a[\mathtt{x} \leftarrow x_0] \land P[\mathtt{x} \leftarrow x_0] \\ \mathtt{slp} \ P \ (c_1; c_2) &= \mathtt{slp} \ (\mathtt{slp} \ P \ c_1) \ c_2 \\ \mathtt{slp} \ P \ (\mathtt{if} \ b \ \mathtt{then} \ c_1 \ \mathtt{else} \ c_2) &= \mathtt{slp} \ (b \land P) \ c_1 \lor \mathtt{slp} \ (\neg b \land P) \ c_2 \\ \mathtt{slp} \ P \ (\mathtt{while}^{\mathit{Inv}} \ b \ \mathtt{do} \ c) &= \neg b \land \mathit{Inv} \\ \mathtt{slp} \ P \ (\mathtt{havoc} \ \mathtt{x}) &= \exists x_0, P[\mathtt{x} \leftarrow x_0] \\ \mathtt{slp} \ P \ (\mathtt{assert} \ A) &= A \land P \end{split}$$

and the nontrivial verification conditions:

$$\begin{array}{l} \operatorname{vc} P\left(\operatorname{while}^{\mathit{Inv}} b \operatorname{do} c\right) = \left(P \Rightarrow \mathit{Inv}\right) \land \left(\operatorname{sp}\left(b \land \mathit{Inv}\right) c \Rightarrow \mathit{Inv}\right) \\ \land \operatorname{vc}\left(b \land \mathit{Inv}\right) c \\ \operatorname{vc} P\left(\operatorname{assert} A\right) = P \Rightarrow A \end{array}$$

Summary

Hoare logics are a rich formalism.

Two complementary viewpoints:

- The axiomatic viewpoint: the rules of the logic define the language.
- The operational viewpoint: the rules are theorems that simplify reasoning about program executions.

Extends rather easily to a great many control structures (goto, break, return, exceptions, procedures, ...).

What about data structures?

(ightarrow next lecture)

References

References

Two presentations of Hoare logic:

- H. R. Nielson and F. Nielson, Semantics with Applications: an appetizer, Springer, 2007, ch. 9 and 10. (Follows the operational approach.)
- G. Winskel, The Formal Semantics of Programming Languages, MIT Press, 1993, ch. 6 and 7.
 (Follows Hoare's axiomatic approach. Comprehensive discussion of completeness issues.)

Mechanizing Hoare logic:

- The companion Coq development for this lecture: https://github.com/xavierleroy/cdf-program-logics
- T. Nipkow and G. Klein, Concrete Semantics, ch. 12.