

Gradual Ownership Types

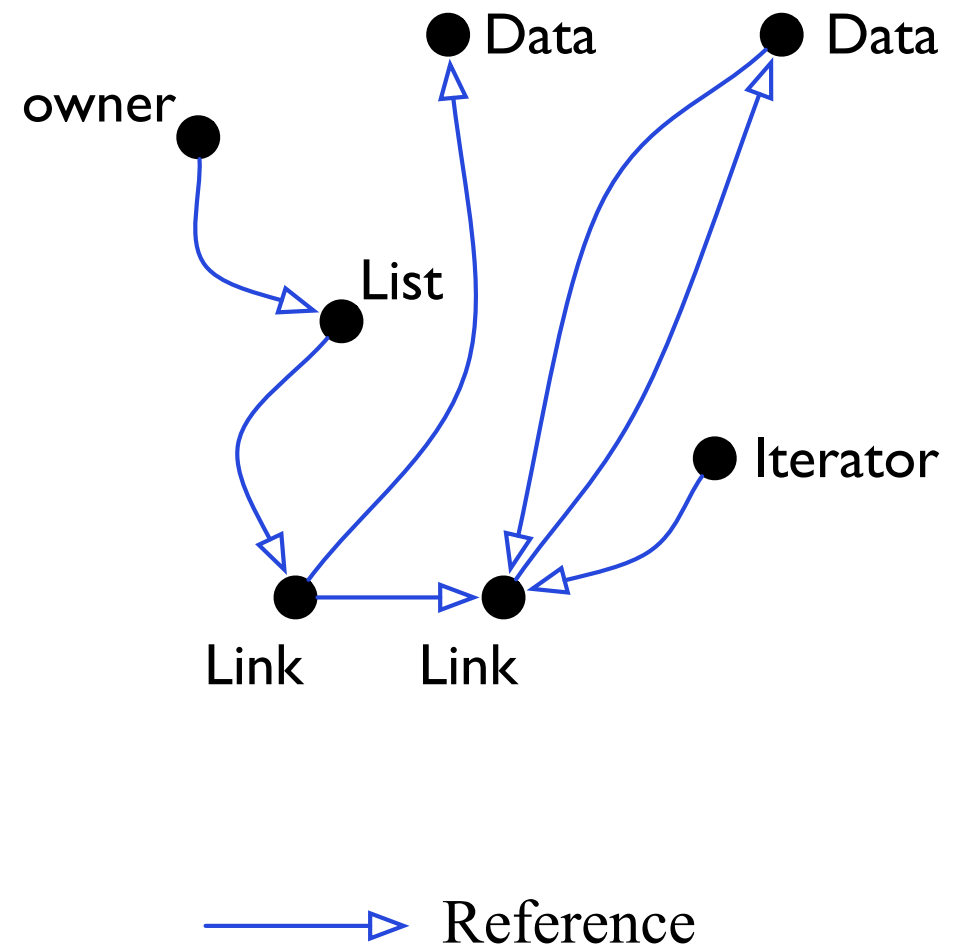
Ilya Sergey Dave Clarke



Ownership Types

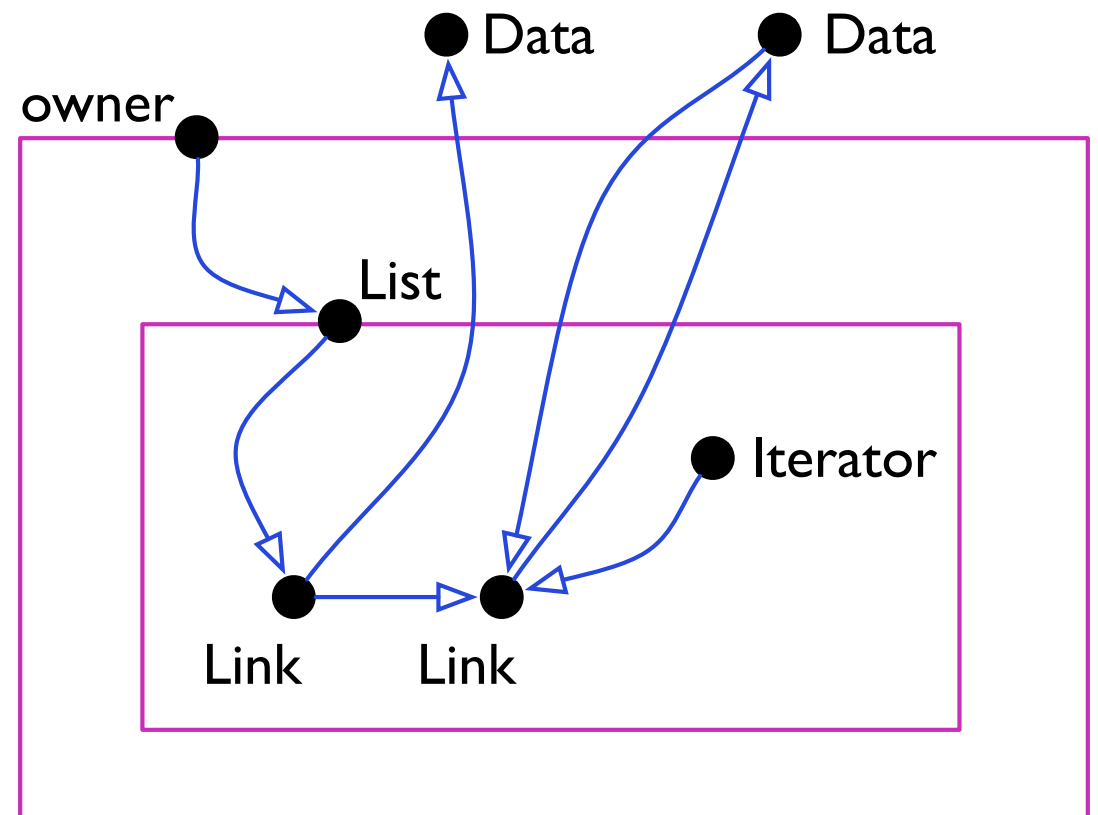
(a gradual introduction)

```
class List {
  Link head;
  void add(Data d) {
    head = new Link(head, d);
  }
  Iterator makeIterator() {
    return new Iterator(head);
  }
}
class Link {
  Link next;
  Data data;
  Link(Link next, Data data) {
    this.next = next; this.data = data;
  }
}
class Iterator {
  Link current;
  Iterator(Link first) {
    current = first;
  }
  void next() { current = current.next; }
  Data elem() { return current.data; }
  boolean done() {
    return (current == null);
  }
}
```



Ownership Types

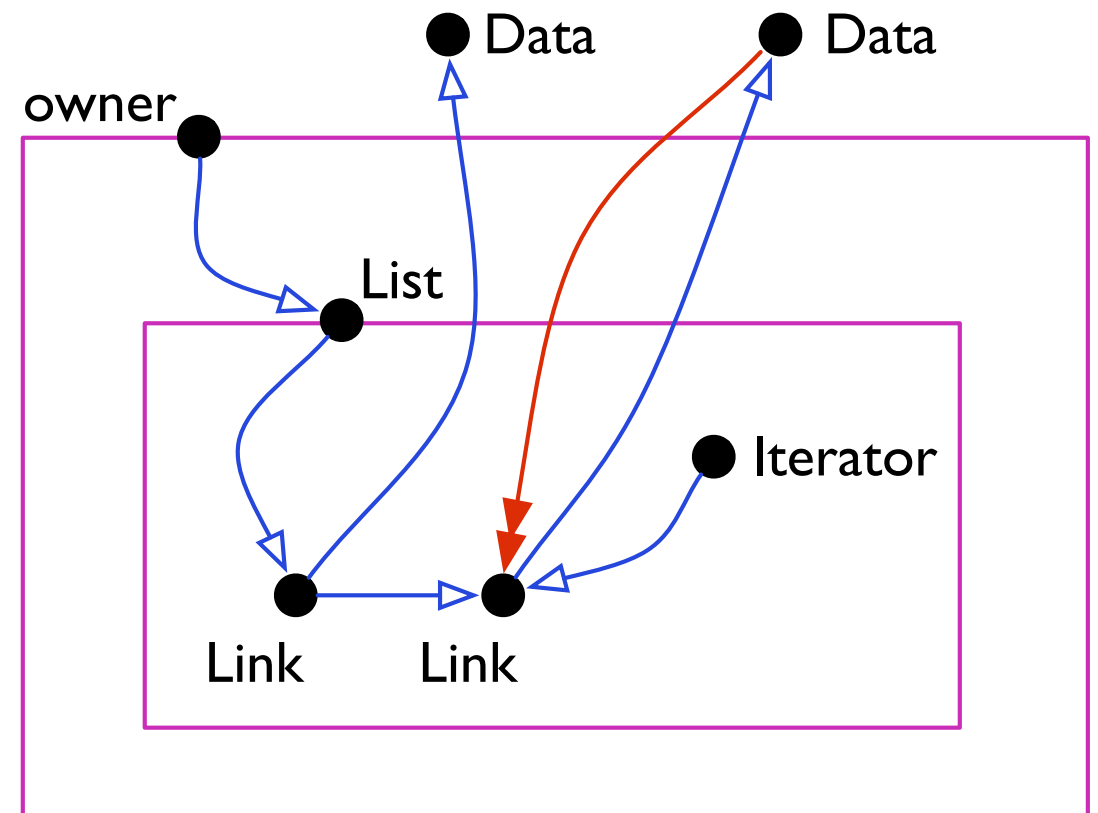
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```



—▶ Reference
— Encapsulation Boundary

Ownership Types

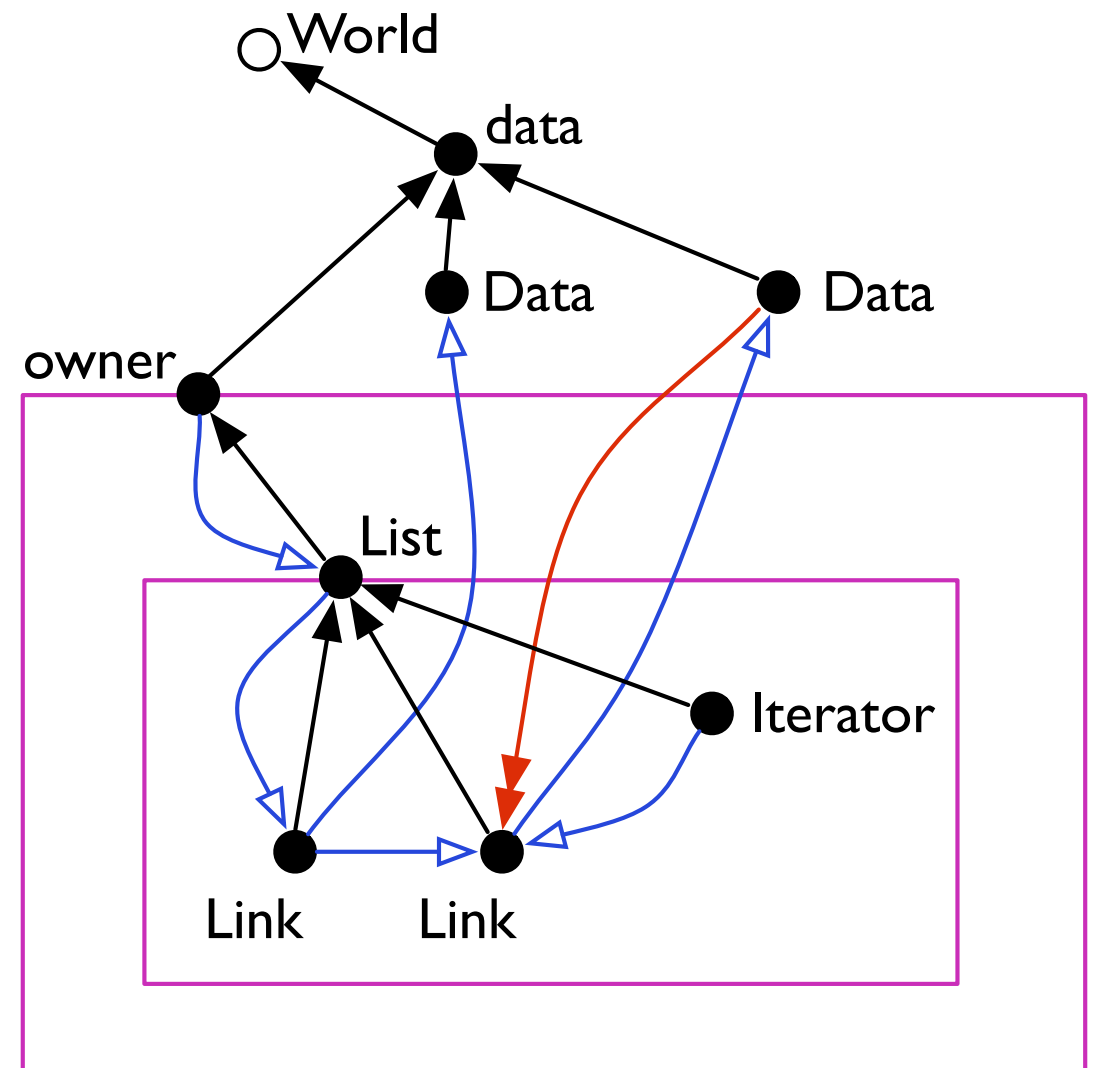
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}
```



—▶ Reference
— Encapsulation Boundary
—▶ Illegal Reference

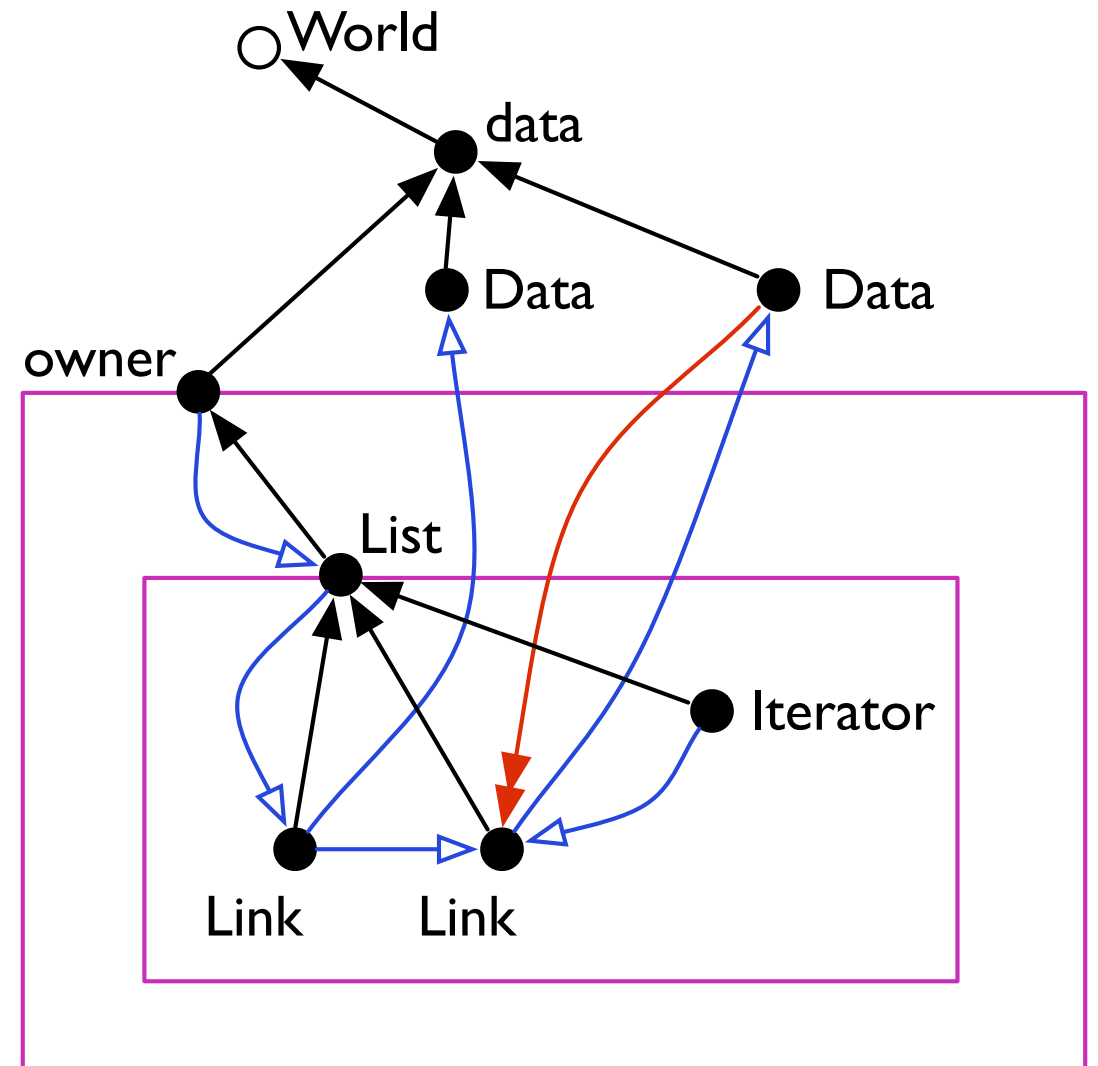
Ownership Types

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```



Ownership Types

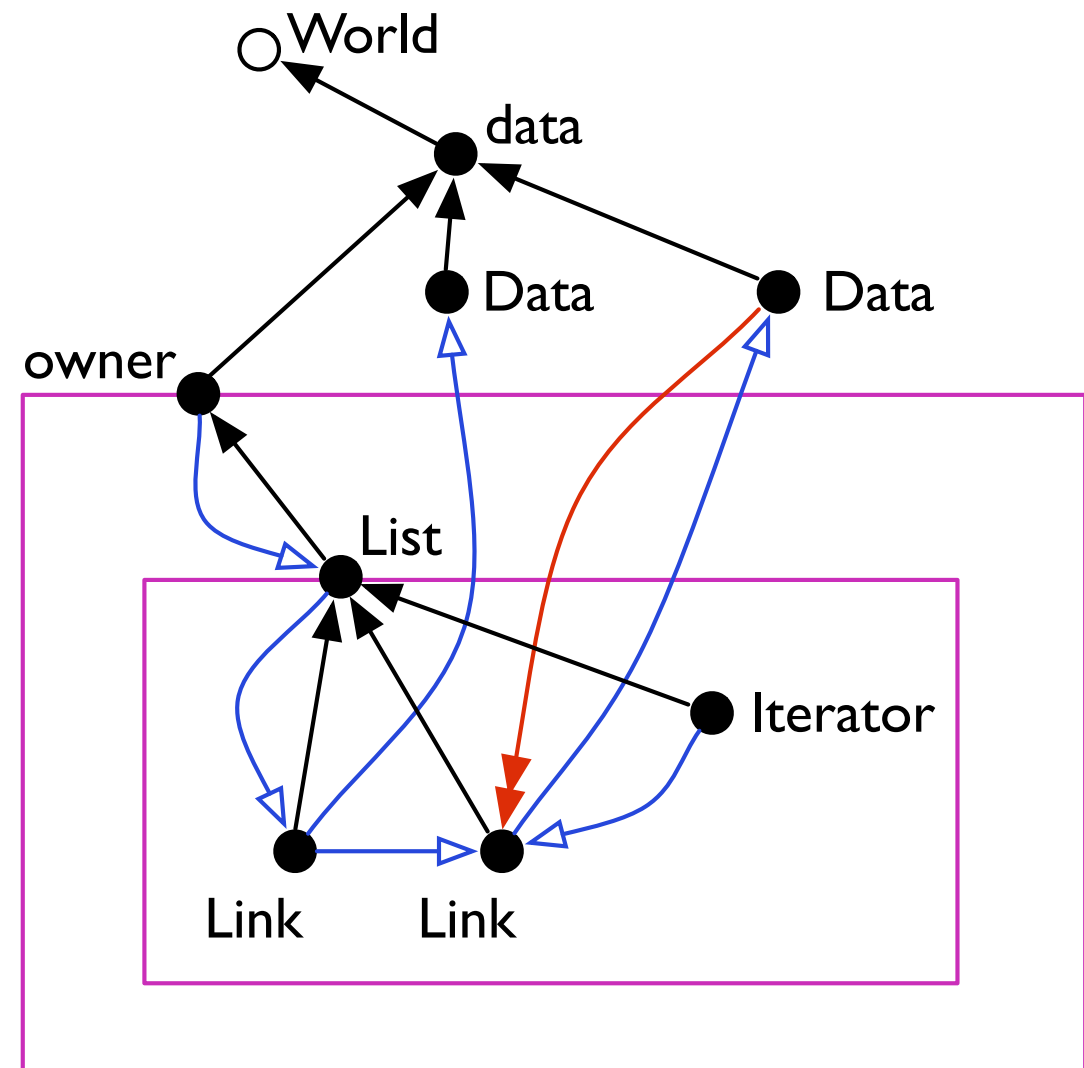
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    return (current == null);
  }
}
```



*Owners-as-Dominators
(OAD)*

Ownership Types

```
class List<owner, data> {
  Link head<this, data>;
  void add(Data<data> d) {
    head = new Link<this, data>(head, d);
  }
  Iterator<this, data> makeIterator() {
    return new Iterator<this, data>(head);
  }
}
class Link<owner, data> {
  Link<owner, data> next;
  Data<data> data;
  Link(Link<owner, data> next, Data<data> data) {
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  }
}
class Iterator<owner, data> {
  Link<owner, data> current;
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  void next() { current = current.next; }
  Data<data> elem() { return current.data; }
  boolean done() {
    return (current == null);
  }
}
```



*Owners-as-Dominators
(OAD)*

Good things about Ownership Types

- data-race freedom [[Boyapati-Rinard:OOPSLA01](#)]
- disjointness of effects [[Clarke-Drossopoulou:OOPSLA02](#)]
- various confinement properties [[Vitek-Bokowski:OOPSLA99](#)]
- effective memory management [[Boyapati-et-al:PLDI03](#)]
- modular reasoning about aliasing [[Müller:VSTTE05](#)]

Bad things about Ownership Types

**Verbose
and
Restrictive**

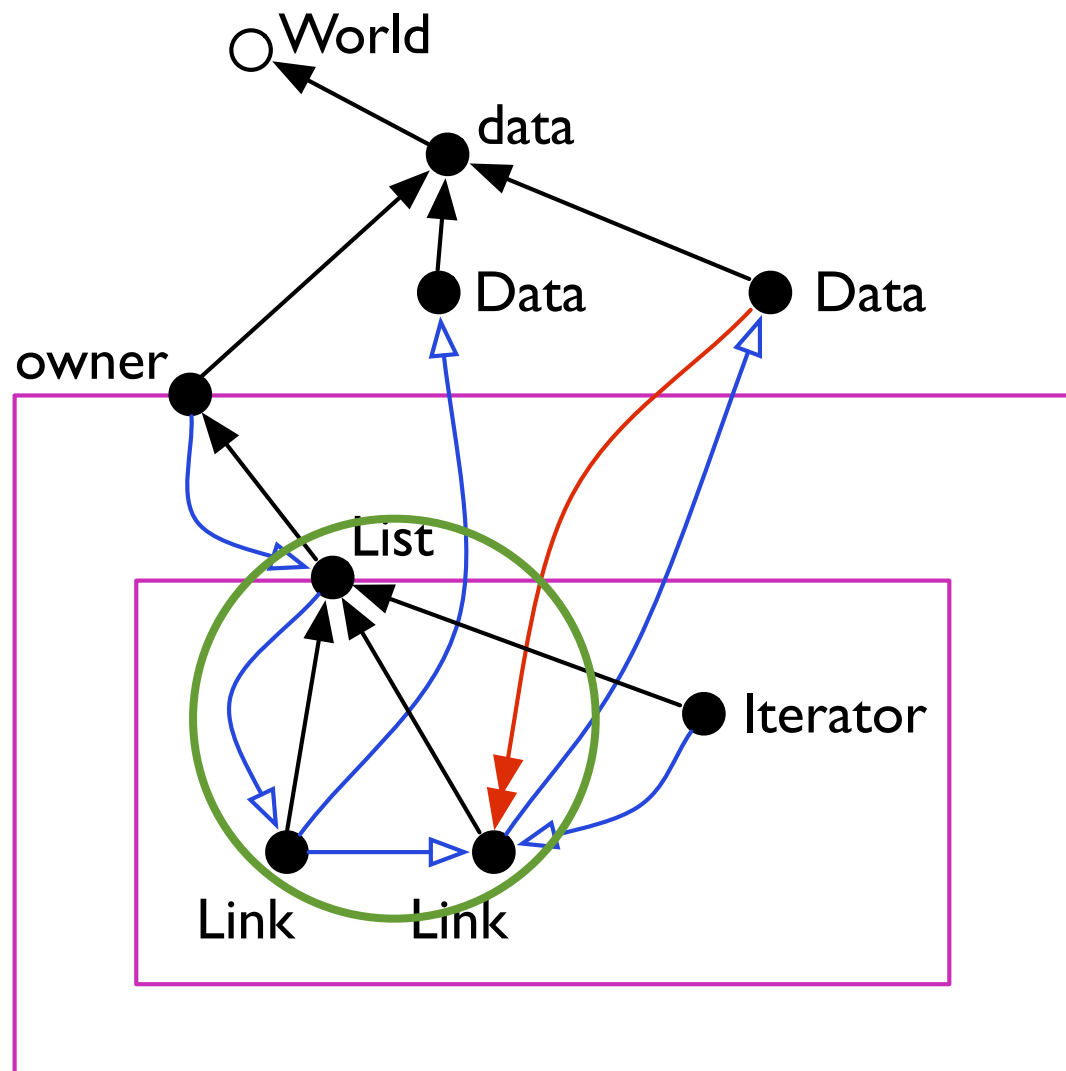
Bad things about Ownership Types

```
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  Data elem() { return current.data; }
  boolean done() {
    return (current == null);
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}
```

```
class List<owner, data> {
  Link head<this, data>;
  void add(Data<data> d) {
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  Iterator<this, data> makeIterator() {
    return new Iterator<this, data>(head);
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}
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  Link<owner, data> next;
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  Link(Link<owner, data> next, Data<data> data) {
    this.next = next; this.data = data;
  }
}
class Iterator<owner, data> {
  Link<owner, data> current;
  Iterator(Link<owner, data> first) {
    current = first;
  }
  void next() { current = current.next; }
  Data<data> elem() { return current.data; }
  boolean done() {
    return (current == null);
  }
}
```

15 annotations

The intention



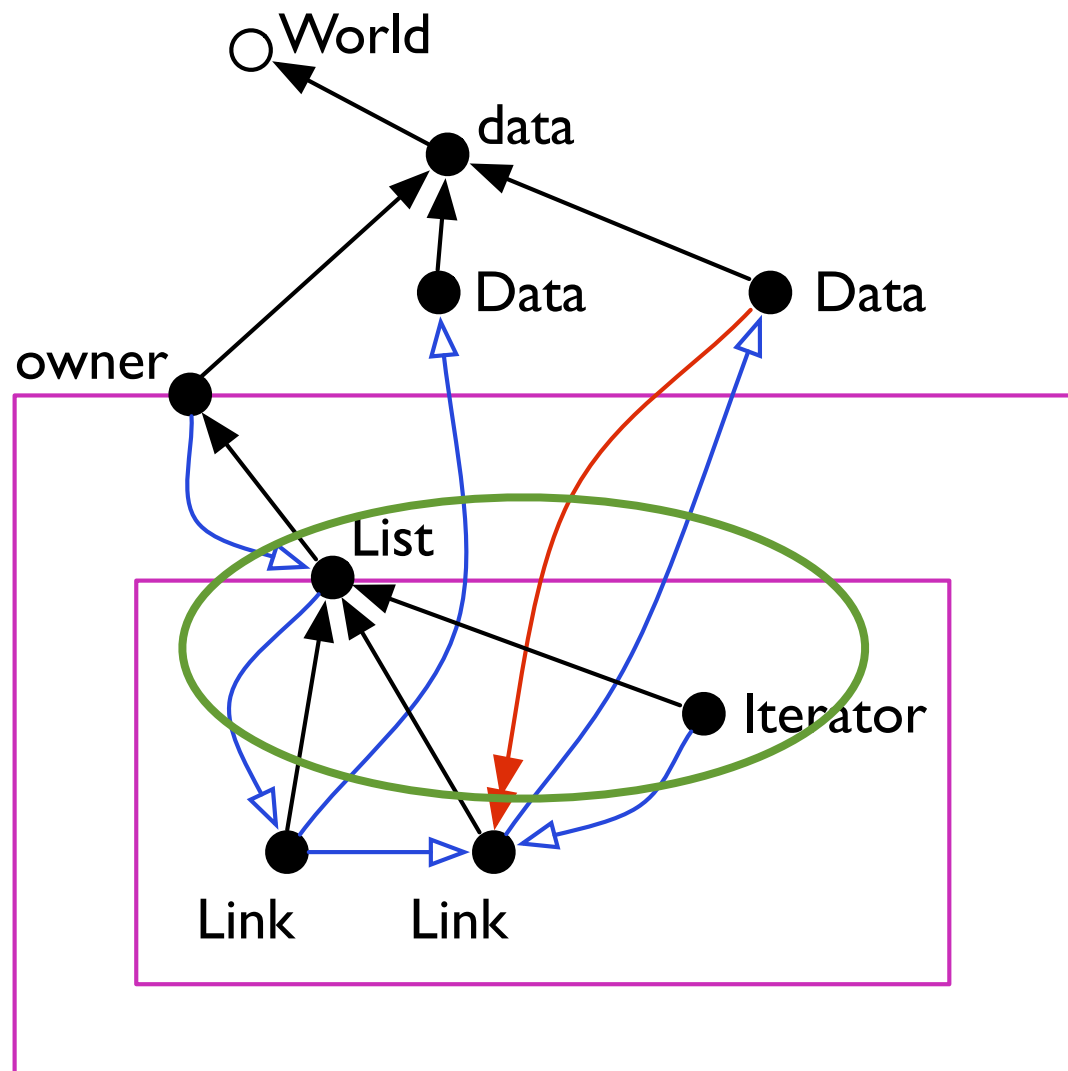
- ▶ Reference
- Encapsulation Boundary
- ▶ Illegal Reference
- ▶ Owner

```
class List<owner, data> {
    Link head<this, data>;
    void add(Data<data> d) {
        head = new Link<this, data>(head, d);
    }
    Iterator<this, data> makeIterator() {
        return new Iterator<this, data>(head);
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class Link<owner, data> {
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    }
}

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```

The intention



- ▶ Reference
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```
class List<owner, data> {
    Link head<this, data>;
    void add(Data<data> d) {
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    }
}

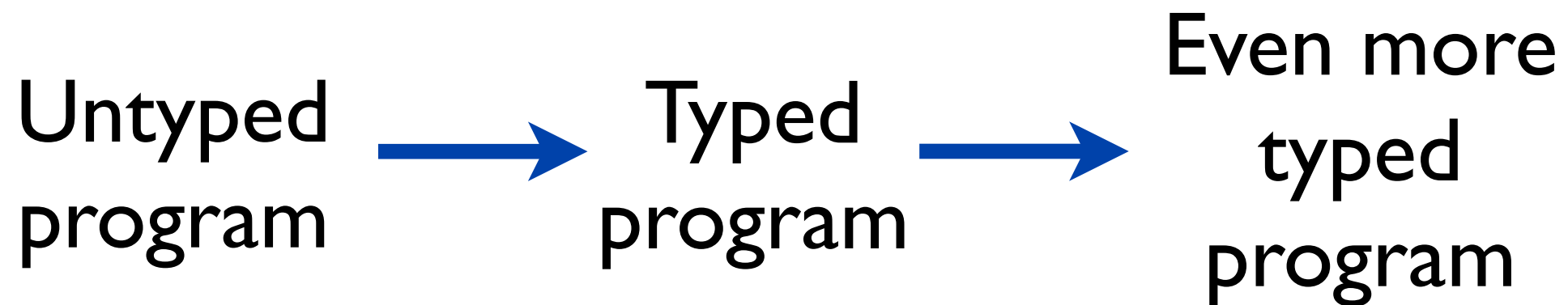
class Link<owner, data> {
    Link<owner, data> next;
    Data<data> data;
    Link(Link<owner, data> next, Data<data> data) {
        this.next = next; this.data = data;
    }
}

class Iterator<owner, data> {
    Link<owner, data> current;
    Iterator(Link<owner, data> first) {
        current = first;
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    }
}
```

Can we implement
the same intention with a
fewer amount of annotations?

A few analogies

- properties of data ~ types
- OAD invariant ~ *more precise types*



From untyped to typed - I

Type Inference

- **SmallTalk** [[Palsberg-Schwartzbach:OOPSLA91](#)]
- **Ruby** [[Fur-An-Foster-Hicks:SAC09](#), [An-Chaudhuri-Foster-Hicks:POPL11](#)]
- **JavaScript** [[Jensen-Møller-Thiemann:SAS10](#), [Guha-al:ESOP11](#)]

Ownership (Type) Inference

- Profiling-based approaches
 - [Wren:MS03](#), [Dietl-Müller:IWACO'07](#)...
- Static CFA-based approaches
 - **Ownership Types:** [Moelius-Souter:MASPLAS04](#), [Huang-Milanova:IWACO11](#), [Milanova-Vitek:TOOLS10](#), [Milanova-Liu:TR10](#), [Dietl-Ernst-Muller:ECOOP11](#) ...
 - **Ownership properties:** [Geilman-Poetzsch-Heffer:IWACO11](#), [Ma-Foster:OOPSLA07](#), [Greenfieldboyce:Foster:OOPSLA07](#), [Aldrich-Kostadinov-Chambers:OOPSLA02](#) ...

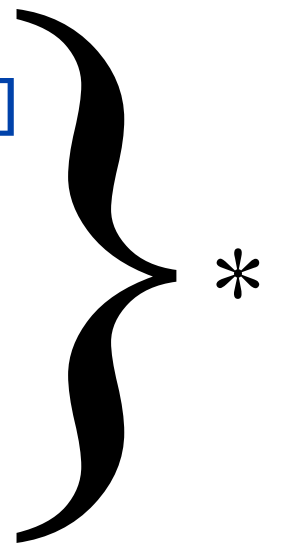
Why not ownership inference?

- Correctness of inference with respect to the type system is *hard* to prove
- Inferred results might be *imprecise* and *difficult* to analyze

From untyped to typed - II

(Partially) relying on dynamic checks

- Gradual Typing [Siek-Taha:ECOOP07, Herman-Tomb-Flanagan:TFP07]
- Hybrid Types [Flanagan:POPL06]
- Contracts [Findler-Felleisen:ICFP02, Gray-Findler-Flatt:OOPSLA05]
- Like types [Wrigstad-ZappaNardelli-Lebresne-Östlund-Vitek:POPL10]



- Dynamic ownership [Gordon-Noble:DLS07]
 - No relation to the type system

* Detailed comparison: Greenberg-Pierce-Weirich:POPL10

Gradual Types

- Programmers may omit type annotations and run the program immediately
 - Run-time checks are *inserted* to ensure *type safety*
- Programmers may add type annotations to increase static checking
 - When all sites are annotated, *all* type errors are caught at compile-time

Gradual Ownership Types

A syntactic type parametrized with owners:

$C\langle \text{owner}, \text{outer} \rangle$

Some owners *might* be *unknown*:

$C\langle ?, \text{outer} \rangle$

Or even all of them:

$C \equiv C\langle ?, ? \rangle$

Type equality: types T_1 and T_2 are *equal*:

$C\langle \text{owner}, \text{outer} \rangle = C\langle \text{owner}, \text{outer} \rangle$

Type equality: types T_1 and T_2 are *consistent*

$C\langle \text{owner}, ? \rangle \sim C\langle ?, \text{outer} \rangle$

I.e., T_1 and T_2 *might* correspond to the *same* runtime values

Traditional Subtyping

```
class D<MyOwner> {...}
class C<Owner1, Owner2> extends D<Owner1> {...}
```

Subtyping: T_1 is a *subtype* of T_2

$C\langle\text{owner}, \text{outer}\rangle \leq D\langle\text{owner}\rangle$

$E;B \vdash t \leq t'$

(SUB-REFL)

$$\frac{E;B \vdash t}{E;B \vdash t \leq t}$$

Reflexive

(SUB-TRANS)

$$\frac{E;B \vdash t \leq t' \quad E;B \vdash t' \leq t''}{E;B \vdash t \leq t''}$$

Transitive

(SUB-CLASS)

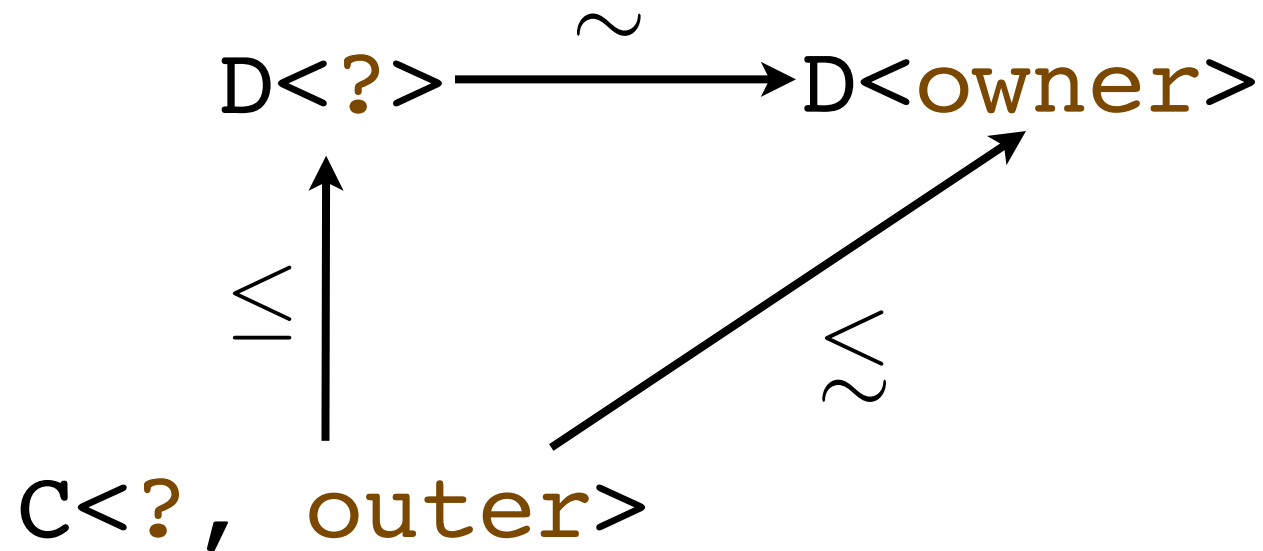
$$\frac{E;B \vdash c\langle\sigma\rangle \quad \text{class } c\langle\alpha_{i \in 1..n}\rangle \text{ extends } c'\langle r_{i \in 1..n'}\rangle \{\dots\}}{E;B \vdash c\langle\sigma\rangle \leq c'\langle\sigma(r_{i \in 1..n'})\rangle}$$

Nominal

Gradual Subtyping

```
class D<MyOwner> {...}
```

```
class C<Owner1, Owner2> extends D<Owner1> {...}
```



$C\langle ?, \text{outer} \rangle \leq D\langle \text{owner} \rangle$

Static semantics

$$E;B \vdash p \sim p'$$

Consistent owners

(CON-REFL)	(CON-RIGHT)	(CON-LEFT)	(CON-DEPENDENT1)	(CON-DEPENDENT2)
$E;B \vdash p$	$E;B \vdash p$	$E;B \vdash p$	$E;B \vdash p \quad E;B \vdash x^{c.i}$	$E;B \vdash p \quad E;B \vdash x^{c.i}$
$E;B \vdash p \sim p$	$E;B \vdash ? \sim p$	$E;B \vdash p \sim ?$	$E;B \vdash p \sim x^{c.i}$	$E;B \vdash x^{c.i} \sim p$

$$E;B \vdash t \leq t'$$

Traditional subtyping

(SUB-REFL)	(SUB-TRANS)	(SUB-CLASS)
$E;B \vdash t$	$E;B \vdash t \leq t' \quad E;B \vdash t' \leq t''$	$E;B \vdash c\langle\sigma\rangle$
$E;B \vdash t \leq t$	$E;B \vdash t \leq t''$	class $c\langle\alpha_{i \in 1..n}\rangle$ extends $c'\langle r_{i \in 1..n'}\rangle\{\dots\}$
		$E;B \vdash c\langle\sigma\rangle \leq c'\langle\sigma(r_i)_{i \in 1..n'}\rangle$

$$E;B \vdash t \sim t'$$

$$E;B \vdash t \lesssim t'$$

$$E;B \vdash t$$

"Good type"

(CON-TYPE)	(GRAD-SUB)	(G-TYPE)
$E;B \vdash c\langle p_{i \in 1..n}\rangle \quad E;B \vdash c\langle q_{i \in 1..n}\rangle$	$E;B \vdash c\langle\sigma\rangle \leq c'\langle\sigma'\rangle$	arity(c) = n
$p_i \sim q_i \forall i \in 1..n$	$E;B \vdash c'\langle\sigma'\rangle \sim c'\langle\sigma''\rangle$	$E;B \vdash p_1 \preceq p_i \quad \forall i \in 1..n$
$E;B \vdash (c\langle p_{i \in 1..n}\rangle \sim c\langle q_{i \in 1..n}\rangle)$	$E;B \vdash (c\langle\sigma\rangle \lesssim c'\langle\sigma''\rangle)$	$E;B \vdash c\langle p_{i \in 1..n}\rangle$

Consistent types

"Gradual Subtyping"

Example I

```
List list; // = List<?,?>  
list = new List<p, world>();  
list = new List<this, world>();  
List<p, world> newList = list;
```



Dangerous assignment!

Example 1

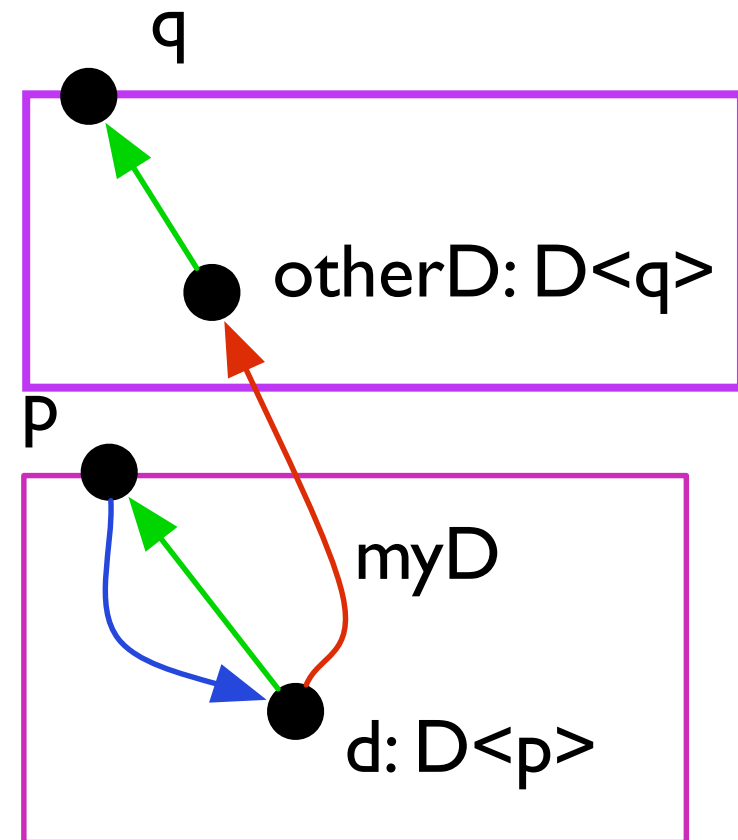
```
List list; // = List<?,?>  
list = new List<p, world>();  
list = new List<this, world>();  
List<p, world> newList =  
    (List<p, world>)list;
```

Dynamic type cast inserted

Example II

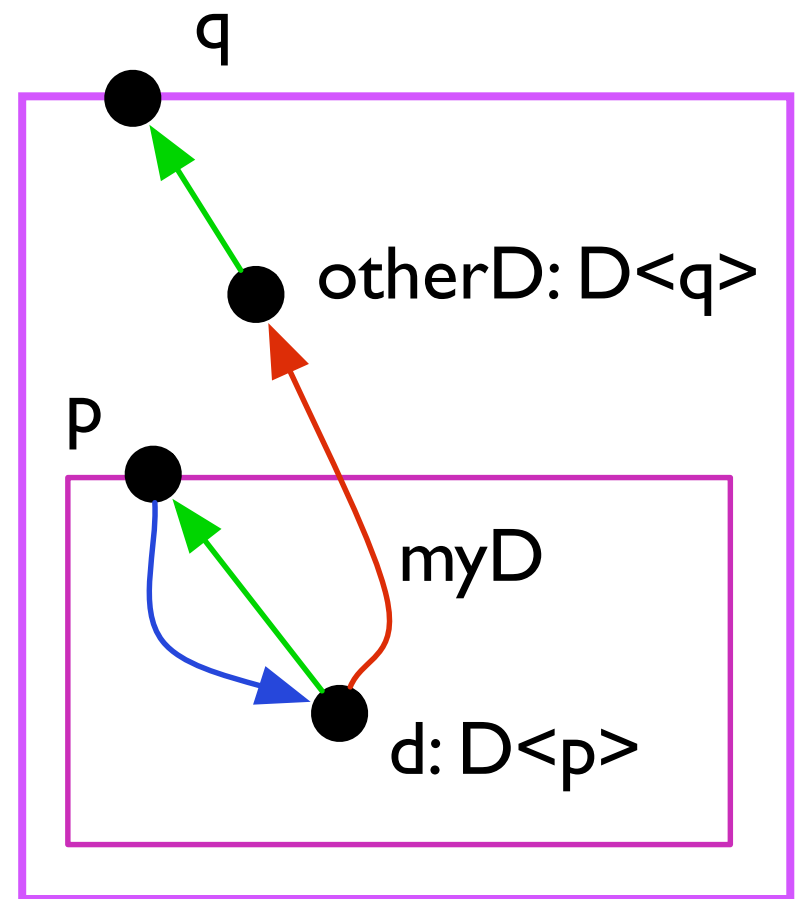
```
class D<owner> {  
    D myD; // = D<?>  
}  
...  
D<q> otherD = ...;  
D<p> d = new D<p>();  
d.myD = otherD;
```

Possible OAD violation



Example II

```
class D<owner> {  
    D myD; // = D<?>  
}  
...  
D<q> otherD = ...;  
D<p> d = new D<p>();  
d.myD =  
bcheck(d, otherD);
```



Boundary check inserted

$d \prec^* \underline{owner}(otherD)$

Type-directed compilation

Dynamic casts and boundary checks are inserted basing on type information.

$$\boxed{E; B \vdash b : s}$$

$$\frac{(T-NEW) \quad E; B \vdash c\langle r_{i \in 1..n} \rangle}{E; B \vdash \text{new } c\langle r_{i \in 1..n} \rangle : c\langle r_{i \in 1..n} \rangle}$$

$$\frac{(T-LKP) \quad E; B \vdash z : c\langle \sigma \rangle \quad \mathcal{F}_c(f) = t}{E; B \vdash z.f : \sigma_z(t)}$$

$$\frac{(T-LET) \quad E; B \vdash b : t \quad E, x : \text{fill}(x, t); B \vdash e : s}{E; B \vdash \text{let } x = b \text{ in } e : s}$$

Field update

$$\frac{(T-UPD) \quad E; B \vdash z : c\langle \sigma \rangle \quad \mathcal{F}_c(f) = t \quad E; B \vdash y : s \quad E; B \vdash s \lesssim \sigma_z(t)}{E; B \vdash z.f = y : \sigma_z(t)}$$

Method call

$$\frac{(T-CALL) \quad E; B \vdash y : s \quad \mathcal{MT}_c(m) = (y', t \rightarrow t') \quad E; B \vdash z : c\langle \sigma \rangle \quad E; B \vdash s \lesssim \sigma_z(t) \quad \sigma' \equiv \sigma \uplus \{y' \mapsto y\}}{E; B \vdash z.m(y) : \sigma'_z(t')}$$

$$\frac{(VAL-w) \quad E; B \vdash \diamond w : s \in E}{E; B \vdash w : s}$$

$$\frac{(VAL-NULL) \quad E; B \vdash t}{E; B \vdash \text{null} : t}$$

$$\boxed{E \vdash t' m(t y) \{e\}}$$

$$\boxed{\vdash P; e}$$

Method return

$$\frac{(METHOD) \quad E, y : \text{fill}(y, t) \vdash e : s \quad E \vdash s \lesssim t'}{E \vdash t' m(t y) \{e\}} \quad \frac{(PROGRAM) \quad \vdash \text{class}_j \quad \forall \text{class}_j \in P \quad E \vdash e : t}{E \vdash P; e}$$

Gradual subtyping might cause check insertion

Type-directed compilation

Two-staged program translation

- Insert *dynamic casts* to coerce types
- Type consistency \Rightarrow Type equality
- Insert *boundary checks* when the invariant can be violated
- Check \prec for unknown owners

Minimal amount of annotations

```
class List<owner, data> {
  Link head<this, data>;
  void add(Data<data> d) {
    head = new Link<this, data>(head, d);
  }
  Iterator<this, data> makeIterator() {
    return new Iterator<this, data>(head);
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}
class Link<owner, data> {
  Link<owner, data> next;
  Data<data> data;
  Link(Link<owner, data> next, Data<data> data) {
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class Iterator<owner, data> {
  Link<owner, data> current;
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    current = first;
  }
  void next() { current = current.next; }
  Data<data> elem() { return current.data; }
  boolean done() {
    return (current == null);
  }
}
```

5 annotations are needed to indicate the intention:

3 annotations to indicate the parametrization

2 annotations for instance owners

10 annotations are optional

Gradual Typing and Compilation (informally)*

Theorem 1:

No unknown owners \Rightarrow no dynamic casts

Corollary :

No unknown owners \Rightarrow static invariant guaranty

(And also, no runtime overhead and failed casts)

Theorem 2:

A (gradually) well-typed program is compiled into a (statically) well-typed program.

* Formal treatment + proofs at <http://people.cs.kuleuven.be/~ilya.sergey/gradual>

Type safety result (informally)

Theorem 3:

A (statically) well-typed program does not violate the OAD invariant but might fail on a dynamic check.

Corollary:

A gradually well-typed program, being compiled, does not violate the OAD invariant.

“Well-typed programs don’t go wrong”
Milner, 1978

Pitfalls of the approach

- Static safety is traded for dynamic checks
- Memory overhead
 - References to owners are stored in objects
- Runtime overhead
 - dynamic boundary checks and type casts

Implementation*

- Implemented in JastAddJ [[Ekman-Hedin:OOPSLA07](#)]
- Extended JastAddJ compiler for Java 1.4
- 2,600 LOC (not including tests and comments)
- Check insertion \Rightarrow compilation warning
- Source-to-source translation

* Available from <http://github.com/ilyasergey/Gradual-Ownership>

Experience

- Java Collection Framework (JDK 1.4.2)
 - 46 source files, ~8,200 LOC
- Securing inner `Entries` of collections
- Questions addressed:
 - How many annotations are needed minimally?
 - What is the execution cost?
 - How many annotations for full static checking?

Experience

- Minimal amount of annotations
 - `LinkedList` - 17
 - `LinkedMap` - 15
- Performance overhead
 - ~1.5-2 times (for extensive updates)
- Full migration
 - `LinkedList` - yes, 34 annotations
 - `LinkedMap` - no, because of static
 - (best - 28 annotations)

Summary

Gradual Ownership Types

- An alternative to ownership inference
- Combines static and dynamic ownership checks, but allows *full static safety*
- Type-directed compilation
- Minimal annotations are unavoidable
- A tradeoff between verbosity and safety

Thanks